

Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application:

1. (Currently amended) A system for the automatic mapping of a user's position relative to an interior of a building, comprising a plurality of interconnected rooms, comprising:

means, transportable by a said user, for generating data indicative of a distance between a said user and walls of a room in which the said user is presently located;

means for locating a said position of said user in said building; and

means for cumulatively mapping the extent of each room in which the said user is located and said user's position relative to said room to produce a map of an interior of said building.

2. (Currently amended) The system for the automatic mapping of a user's position relative to an interior of a building of claim 1 wherein said means for generating data comprises:

means for transmitting a signal toward said walls of said room;

means for receiving components of said transmitted signal reflected off said walls of said room; and

means for determining a distance from said user to said walls as a function of the time difference between transmitting said signal and receipt of said reflected components of said transmitted signal.

3. (Currently amended) The system for the automatic mapping of a user's position relative to an interior of a building of claim 2 wherein said means for generating data further comprises:

means for identifying a presence of an opening in said walls.

Serial No. 09/733,121

Page 2 of 11

304282v1

Response to Office Action mailed 30 Sep 2004

4. (Currently amended) The system for the automatic mapping of a user's position relative to an interior of a building of claim 1 wherein said means for generating data comprises:

means for concurrently measuring a distance between a user and a plurality of walls of a room in which the user is presently located.

5. (Currently amended) The system for the automatic mapping of a user's position relative to an interior of a building of claim 1 wherein said means for locating comprises:

inertial guidance means for dynamically measuring movement of said user as said user moves through said rooms of said building.

6. (Currently amended) The system for the automatic mapping of a user's position relative to an interior of a building of claim 5 wherein said means for locating further comprises:

means for dynamically measuring movement of said user using at least one of movement sensors comprising: gyroscope, accelerometer, rotation detector.

7. (Currently amended) The system for the automatic mapping of a user's position relative to an interior of a building of claim 1 wherein said means for cumulatively mapping comprises:

means for creating a virtual map of said building using said generated distance data and said user location data for each room traversed by said user.

8. (Currently amended) The system for the automatic mapping of a user's position relative to an interior of a building of claim 1 further comprising:

sensor means for measuring at least one of building and user parameters: ambient temperature, presence of toxic gasses, oxygen level in a breathing tank, time to exhaustion of breathable air in the breathing tank, user breathing rate and heart rate sensors, user time in area, a user failure to move indicator, command and control alerts,

text readout of messages from the command and control system, voice activation of the unit including the display, location of other users in the vicinity, warning indications.

9. (Currently amended) The system for the automatic mapping of a user's position relative to an interior of a building of claim 1 further comprising:
means for displaying said map to said user.

10. (Currently amended) A method of automatic mapping of a user's position relative to an interior of a building, comprising a plurality of interconnected rooms, comprising the steps of:

generating, using apparatus transportable by a said user, data indicative of a distance between a said user and walls of a room in which the said user is presently located;

~~means for locating a position of said user in said building; and~~

~~means for cumulatively mapping the extent of each room in which the said user is located and said user's position relative to said room to produce a map of an interior of said building.~~

11. (Currently amended) The method of automatic mapping of a user's position relative to an interior of a building of claim 10 wherein said step of generating data comprises:

transmitting a signal to said walls of said room;

receiving components of said transmitted signal reflected off said walls of said room; and

determining a distance from said user to said walls as a function of the time difference between transmitting said signal and receipt of said reflected components of said transmitted signal.

12. (Currently amended) The method of automatic mapping of a user's position relative to an interior of a building of claim 11 wherein said step of generating data further comprises:

identifying a presence of an opening in said walls.

13. (Currently amended) The method of automatic mapping of a user's position relative to an interior of a building of claim 10 wherein said step of generating data comprises:

concurrently measuring a distance between a user and a plurality of walls of a room in which the user is presently located.

14. (Currently amended) The method of automatic mapping of a user's position relative to an interior of a building of claim 10 wherein said step of locating comprises:

dynamically measuring movement of said user via an inertial guidance apparatus for as said user moves through said rooms of said building.

15. (Currently amended) The method of automatic mapping of a user's position relative to an interior of a building of claim 14 wherein said step of locating further comprises:

dynamically measuring movement of said user using at least one of movement sensors comprising: gyroscope, accelerometer, rotation detector.

16. (Currently amended) The method of automatic mapping of a user's position relative to an interior of a building of claim 10 wherein said step of cumulatively mapping comprises:

creating a virtual map of said building using said generated distance data and said user location data for each room traversed by said user.

17. (Currently amended) The method of automatic mapping of a user's position relative to an interior of a building of claim 10 further comprising the step of:

measuring at least one of building and user parameters: ambient temperature, presence of toxic gasses, oxygen level in a breathing tank, time to exhaustion of breathable air in the breathing tank, user breathing rate and heart rate sensors, user time in area, a user failure to move indicator, command and control alerts, text readout of messages from the command and control system, voice activation of the unit including the display, location of other users in the vicinity, warning indications.

18. (Currently amended) The method of automatic mapping of a user's position relative to an interior of a building of claim 10 further comprising the step of:

displaying said map to said user.

19. (Currently amended) A system for the automatic mapping a user's position relative to of an interior of a building, comprising a plurality of interconnected rooms, comprising:

tracker module means, transportable by a said user, comprising:

transducer means for generating data indicative of a distance between a user and walls of a room in which the said user is presently located,

inertial guidance means for generating data indicative of a position of said user in said building; and

command module means for cumulatively mapping the extent of each room in which the said user is located and said user's position relative to said room to produce a map of an interior of said building.

20. (Currently amended) The system for the automatic mapping of a user's position relative to an interior of a building of claim 19 wherein said transducer means comprises:

transmitter means for transmitting a signal to said walls of said room,

Serial No. 09/733,121

Response to Office Action mailed 30 Sep 2004

Page 6 of 11

304282v1

receiver means for receiving components of said transmitted signal reflected off said walls of said room; and

computing means for determining a distance from said user to said walls as a function of the time difference between transmitting said signal and receipt of said reflected components of said transmitted signal.

21. (Currently amended) The system for the automatic mapping of a user's position relative to an interior of a building of claim 20 wherein said transducer means further comprises:

doorway detecting means for identifying a presence of an opening in said walls.

22. (Currently amended) The system for the automatic mapping of a user's position relative to an interior of a building of claim 19 wherein said transducer means comprises:

means for concurrently measuring a distance between a said user and a plurality of walls of a room in which the said user is presently located.

23. (Currently amended) The system for the automatic mapping of a user's position relative to an interior of a building of claim 19 wherein said inertial guidance means comprises:

accelerometer means for dynamically measuring movement of said user as said user moves through said rooms of said building.

24. (Currently amended) The system for the automatic mapping of a user's position relative to an interior of a building of claim 19 wherein said inertial guidance means comprises:

gyroscope means for dynamically measuring movement of said user as said user moves through said rooms of said building.

Serial No. 09/733,121

Page 7 of 11

304282v1

Response to Office Action mailed 30 Sep 2004

25. (Currently amended) The system for the automatic mapping of a user's position relative to an interior of a building of claim 19 wherein said inertial guidance means comprises:

movement sensor means for dynamically measuring movement of said user using at least one of movement sensors comprising: gyroscope, accelerometer, rotation detector.

26. (Currently amended) The system for the automatic mapping of a user's position relative to an interior of a building of claim 19 wherein said command module means comprises:

mapping means for creating a virtual map of said building using said generated distance data and said user location data for each room traversed by said user.

27. (Currently amended) The system for the automatic mapping of a user's position relative to an interior of a building of claim 19 wherein said tracker module means further comprises:

sensor means for measuring at least one of building and user parameters: ambient temperature, presence of toxic gasses, oxygen level in a breathing tank, time to exhaustion of breathable air in the breathing tank, user breathing rate and heart rate sensors, user time in area, a user failure to move indicator, command and control alerts, text readout of messages from the command and control system, voice activation of the unit including the display, location of other users in the vicinity, warning indications.

28. (Currently amended) The system for the automatic mapping of a user's position relative to an interior of a building of claim 19 wherein said tracker module means further comprises:

heads-up display means for displaying said map to said user.